

Bisimulations for Algebraic Effects

Some Preliminary Results

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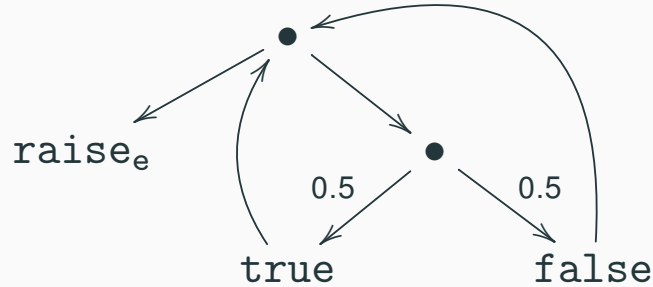
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Introduction

What is this talk about?

```
coinGame = (raisee ⊕ (true ⊕0.5 false)) :: coinGame
```



```
coinGame1 = ((raisee ⊕ true) ⊕0.5 (false ⊕ raisee)) :: coinGame1
```

Question

What is the relationship between `coinGame` and `coinGame1`?

What is this talk about?

```
simpleGame = λn,score ->  
  (simpleGame 1 0 ⊕ score) ⊕  $\frac{1}{2n}$   
  (simpleGame n+1 score+1 ⊕ 0.5 simpleGame n+1 score)
```

```
game = λn,score ->  
  ((game 1 0 ⊕  $\frac{2}{n+1}$  game n+1 score+1) ⊕  $\frac{n+1}{2n}$  game n+1 score) ⊕  
  (score ⊕  $\frac{1}{n}$  (game n+1 score+1 ⊕ 0.5 game n+1 score))
```

Question

What is the relationship between game and simpleGame?

What is this talk about?

```
spine =  $\lambda n \rightarrow n \oplus$  spine (n+1)
```

```
nonDetNat = spine 0
```

```
nats =  $\lambda n \rightarrow n ::$  nats (n+1)
```

```
nonDetNat1 = foldr  $\oplus$  _ (nats 0) -- nats 0 infinite list
```

```
doubleSpine =  $\lambda n \rightarrow (n \oplus n) \oplus$  doubleSpine (n+1)
```

```
doubleNonDetNat = doubleSpine 0
```

Moral

Reasoning about programs with side effects is hard.

What is this talk about?

- **Monads** are used to deal with side effects in a functional way.
- However, due to their generality, monads come equipped with few functionalities (`join`, `return`, `»=...`)
↳ monadic programming is not easy, and reasoning about monadic programs is even harder.
- To make programming easier, one often defines **specific operations on monads** (small domain specific language for families of side effects).
- G.D. Plotkin and A.J. Power: Adequacy for algebraic effects ↳ side effects generated by **algebraic operations**.

What is this talk about?

Example

- Exceptions: $T(X) = X + E$, *raise_e*
- Non-determinism: $T(X) = \mathcal{P}(X)$, \oplus
- Probabilistic Computations: $T(X) = \mathcal{D}(X)$, \oplus_p
- Global State: $T(X) = S \Rightarrow (S \times S)$, *write, read*

Question

Are things simpler if we focus on monadic programs built using domain specific operations? *Yes, they are!*

Goals

- State of the art: coinductive techniques for e.g. λ -calculi with non-deterministic choice, errors, probabilistic choice etc.
- But these results are very specific to the languages considered.

Goal

Come up with general coinductive techniques **parametric over monads and operations**

~> Coinductive reasoning for families of domain specific monadic languages for free.

Results

- We studied CbN effectful untyped λ -calculus.
- We defined a general and intuitive notion of **applicative bisimulation** and prove it is **sound and complete wrt contextual equivalence**.
- The framework is general and surprisingly easy.
- It generalizes most of the specific notions of bisimulations given so far.
- We developed a number of **up-to techniques** that allow simple equational reasoning over programs.

$$\begin{aligned} \lambda x. \lambda y. x \oplus (x \oplus y) \sim \lambda x. \lambda y. y \oplus x &\Leftarrow x \oplus (x \oplus y) \approx y \oplus x \\ &\Leftarrow (x \oplus x) \oplus y \approx y \oplus x \\ &\Leftarrow x \oplus y \approx y \oplus x \\ &\Leftarrow y \oplus x \approx y \oplus x \end{aligned}$$

Bisimulations for Algebraic Effects

- The basic language we consider is untyped λ -calculus.
- Side effects via a monad T . The result of a program is then an elements of $T(\text{Values})$.

Example

- Non-termination: values are elements of $\text{Values} + \{\perp\}$.
- Non-determinism: values are elements of $\mathcal{P}(\text{Values})$.
- Probabilistic non-determinism: values are elements of $\mathcal{D}(\text{Values})$.

- We need a monad T and a signature Σ of operation symbols:

$$t ::= x \mid \lambda x. t \mid tt \mid \text{op}(t, \dots, t)$$

- For each n -ary operation op an interpretation:
 $\text{op}^T : T(X)^n \rightarrow T(X)$
- We model computations using domain-theoretic concepts: we require $T(X)$ to be a **dcpo**.
- Concretely, we want a functor $T : \text{Set} \rightarrow \Sigma\text{-dcpo}$ such that T carries a monadic structure under the forgetful functor.

Remark

Most of the monads used in programming satisfy these conditions (e.g. all the above ones).

Some Examples

- **Non-termination:** $T(X) = X + \{\perp\}$

No operations. $X + \{\perp\}$ is a dcpo (flat domain) with least element \perp .

- **Non-determinism:** $T(X) = \mathcal{P}(X)$

There is a binary operation \oplus for **non-deterministic choice** interpreted as set-theoretic union. $\mathcal{P}(X)$ is a dcpo under the inclusion order.

- **Probabilistic computations:** $T(X) = \mathcal{D}(_)$

We have a family of binary operations \oplus_p parametrized over $p \in [0, 1]$. \oplus_p is interpreted as **probabilistic choice** ($x \oplus_p y = p \cdot x + (1 - p) \cdot y$). $\mathcal{D}(X)$ is a dcpo under the pointwise order.

- Having to reason about side effects, we focus on **computations** rather than on programs.
- Indeed **side effects occur during the execution of a program**.

Definition

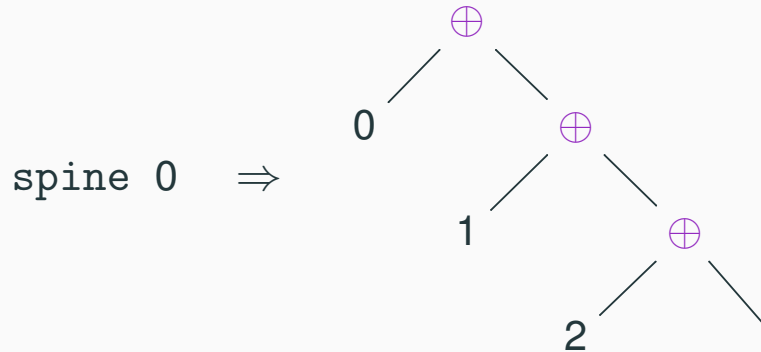
The execution of a program is the possibly infinite tree recording all the side effects that could occur during a run of the program.

Example

Consider the program

$$\text{spine} = \lambda n \rightarrow n \oplus (\text{spine } n+1)$$

The evaluation of the program `spine 0` is the **infinite tree**



i.e. the infinite term $0 \oplus 1 \oplus 2 \oplus \dots \oplus n \oplus \dots$

- Computation trees (infinitary Σ -terms) over values $CT(\mathcal{V})$ are defined coinductively:

$$\frac{}{\perp \in CT(\mathcal{V})} \quad \frac{}{\lambda x.t \in CT(\mathcal{V})} \quad \frac{ct_1, \dots, ct_n \in CT(\mathcal{V})}{\text{op}(ct_1, \dots, ct_n) \in CT(\mathcal{V})}$$

Theorem

$CT(X)$ is a dcpo under the approximation order (\perp is the totally undefined tree). Moreover, it is *initial* in the category of Σ -dcpo and *final* in the category of Σ -algebras.

Initiality \Rightarrow inductive operational semantics

Finality \Rightarrow coinductive operational semantics

Observational Equivalences

- We are interested in **observationally indistinguishable** programs
 \rightsquigarrow **contextual equivalence**;

“With respect to **some choice of observation**, two terms t, u are contextual equivalent, notation $t \equiv^{ctx} u$, if for all contexts $C[]$, the **observations** on $C[t]$ and $C[u]$ **agree** ...”

— Winskel, The Formal Semantics of Programming Languages

- The notion of observation is left on an informal level.
- What is observable of a program is usually implicitly determined by contextual equivalence itself.

Observational Equivalences

- In **pure untyped** λ -calculus contextual equivalence is defined by

$$t \equiv^{ctx} u \quad \text{iff} \quad \forall C[\]. C[t] \downarrow \Leftrightarrow C[u] \downarrow .$$

We thus observe **convergence**.

- In **probabilistic** λ -calculus contextual equivalence is defined by

$$t \equiv^{ctx} u \quad \text{iff} \quad \forall C[\]. Pr(C[t] \downarrow) = Pr(C[u] \downarrow) .$$

We thus observe the **probability of convergence**.

- In **non-deterministic** λ -calculus contextual equivalence is defined by

$$t \equiv^{ctx} u \quad \text{iff} \quad \forall C[\]. \exists v. C[t] \downarrow v \Leftrightarrow \exists w. C[u] \downarrow w .$$

We thus observe **may convergence**.

Our Starting Point

- General and formal notion of observation **parametric over monads and operations**.
- Two basic assumptions:
 - We can only **observe side effects**
 - We observe the **the executions of a program**.

Observational Equivalences

- In untyped calculi it is usually assumed values to be observationally indistinguishable. We define a notion of observation according to this assumption (**but this is not required**).

Definition

Let $1 = \{*\}$ be a one element set. **Observation** is the function $obs : CT(\mathcal{V}) \rightarrow T(1)$ defined by

$$obs(\perp) = \perp_T$$

$$obs(v) = \eta(*)$$

$$obs(\text{op}(ct_1, \dots, ct_n)) = \text{op}^T(obs(ct_1), \dots, obs(ct_n))$$

Some Examples

- **Pure λ -calculus:** $obs : CT(\mathcal{V}) \rightarrow 1 + \{\perp\}$

$$obs(\perp) = \perp$$

$$obs(v) = *$$

$$obs(t) = \{*\} \Leftrightarrow t \downarrow$$

- **Non-deterministic λ -calculus:** $obs : CT(\mathcal{V}) \rightarrow \mathcal{P}(1)$

$$obs(\perp) = \emptyset$$

$$obs(v) = \{*\}$$

$$obs(ct_1 \oplus ct_2) = obs(ct_1) \cup obs(ct_2)$$

$$obs(t) = \{*\} \Leftrightarrow t \text{ may converge}$$

Some Examples

- Probabilistic λ -calculus: $obs : CT(\mathcal{V}) \rightarrow \mathcal{D}(1) \cong [0, 1]$

$$obs(\perp) = 0$$

$$obs(v) = 1$$

$$obs(ct_1 \oplus_p ct_2) = p \cdot obs(ct_1) + (1 - p) \cdot obs(ct_2)$$

$$obs(t) = Pr[t \downarrow]$$

- λ -calculus with states: $obs : CT(\mathcal{V}) \rightarrow (1 \times S)^S \cong S \rightarrow S$

Omitting details, $obs(t)$ is a partial function associating initial and final states to the execution of t , if t converges, and undefined otherwise.

Observational Equivalences

- Observing a term corresponds to observing its execution:

$$obs(t) \stackrel{def}{=} obs(eval(t)).$$

- We can now take Winskel's definition and make it formal:

Definition

With respect to a choice of observation *obs*, two terms *t*, *u* are contextual equivalent, notation $t \equiv^{ctx} u$, if for all contexts $C[]$

$$obs(C[t]) = obs(C[u]).$$

From Contextual Equivalence to Applicative Bisimulation

- Proving that two programs are contextual equivalent is hard (due to universal quantification).
- We can give a sound and complete **coinductive** characterization of contextual equivalence \rightsquigarrow **easier proof techniques**.
- Two programs are **bisimilar** if **observations cannot distinguish them**, and this property is **invariant under further computations** (i.e. application).

Remark

Usually bisimulation defined by means of relations that **implicitly encode a notion of observation**. This leads to definitions involving relation lifting and makes proofs quite involved.

Using an **explicit notion of observation over executions of programs** gives **surprisingly easy proofs**.

Example

$$\begin{array}{ccc} t_1 \stackrel{\text{def}}{=} \lambda x. t \oplus u & & t_2 \stackrel{\text{def}}{=} \lambda x. t \oplus \lambda x. u \\ \Downarrow & & \Downarrow \\ ct_1 \stackrel{\text{def}}{=} \lambda x. t \oplus u & & ct_2 \stackrel{\text{def}}{=} \begin{array}{c} \oplus \\ / \quad \backslash \\ \lambda x. t \quad \lambda x. u \end{array} \end{array}$$

We have $obs(ct_1) = obs(ct_2)$. This property is **invariant under application**:

$$\begin{array}{ccc} t_1 s \Rightarrow & \begin{array}{c} \oplus \\ / \quad \backslash \\ t\{s/x\} \quad u\{s/x\} \end{array} & t_2 s \Rightarrow \begin{array}{c} \oplus \\ / \quad \backslash \\ t\{s/x\} \quad u\{s/x\} \end{array} \end{array}$$

where $t\{u/x\}$ denotes $eval(t[u/x])$.

Definition

A symmetric relation $\mathcal{R} \subseteq CT(\mathcal{V}) \times CT(\mathcal{V})$ is an **applicative bisimulation** if whenever $ct_1 \mathcal{R} ct_2$ we have

- $obs(ct_1) = obs(ct_2)$;
- For any term t , $ct_1\{t/x\} \mathcal{R} ct_2\{t/x\}$.

Bisimilarity \sim is defined as the largest applicative bisimulation.

- $ct\{t/x\}$ is the computation tree obtained from ct by replacing all leaves (which are of the form $\lambda x. u$) with $eval(u[t/x])$.

Theorem (Full Abstraction)

$$t \equiv^{ctx} u \iff t \sim u$$

- The proof is via CIU using a straightforward generalization of Howe's technique for the pure λ -calculus.

Theorem (Up-to Equations)

Every equational theory over computation trees which is sound in the monad is contained in \sim .

- Powerful **up-to technique**.
- Extremely useful since several monads have an equational presentation.
- Syntactical proofs for contextual equivalence.

Examples (Optional)

- Equational theory for non-deterministic choice

$$x \oplus x \approx x$$

$$x \oplus y \approx y \oplus x$$

$$x \oplus (y \oplus z) \approx (x \oplus y) \oplus z$$

This theory is **sound** in $\mathcal{P}(\mathcal{V})$ with the \oplus interpreted as \cup . As a consequence, we have

$$ct_1 \approx ct_2 \Rightarrow ct_1 \sim ct_2$$

Examples (Optional)

- Equational theory for probabilistic non-determinism:

$$x \oplus_1 y \approx x$$

$$x \oplus_p x \approx x$$

$$x \oplus_p y \approx y \oplus_{1-p} x$$

$$(x \oplus_p y) \oplus_q z \approx x \oplus_{pq} (y \oplus_{\frac{q(1-p)}{1-pq}} z)$$

This theory is **sound** in $\mathcal{D}(\mathcal{V})$ with the \oplus interpreted as **probabilistic choice**. As a consequence, we have

$$ct_1 \approx ct_2 \Rightarrow ct_1 \sim ct_2$$

- The equational theory for probabilistic and non-deterministic choice is obtained from the above one plus the equation

$$x \oplus (y \oplus_p z) \approx (x \oplus_p y) \oplus (x \oplus_p z)$$

Examples (Optional)

Recall the following programs

```
simpleGame =  $\lambda n, score \rightarrow$   
  (simpleGame 1 0  $\oplus$  score)  $\oplus \frac{1}{2n}$   
  (simpleGame n+1 score+1  $\oplus 0.5$  simpleGame n+1 score)
```

```
game =  $\lambda n, score \rightarrow$   
  ((game 1 0  $\oplus \frac{2}{n+1}$  game n+1 score+1)  $\oplus \frac{n+1}{2n}$  game n+1 score)  $\oplus$   
  (score  $\oplus \frac{1}{n}$  (game n+1 score+1  $\oplus 0.5$  game n+1 score))
```

We show $\text{simpleGame} \sim \text{game}$. Let

$M = \text{simpleGame } 1 \ 0$

$N = \text{score}$

$P = \text{simpleGame } n+1 \ \text{score}+1$

$Q = \text{simpleGame } n+1 \ \text{score}$

Examples (Optional)

From

$$\begin{aligned}(M \oplus N) \oplus_{\frac{1}{2n}} (P \oplus_{\frac{1}{2}} Q) &\approx (M \oplus_{\frac{1}{2n}} (P \oplus_{\frac{1}{2}} Q)) \oplus (N \oplus (P \oplus_{\frac{1}{2}} Q)) \\ &\quad \{ \text{by } x \oplus (y \oplus_p z) \approx (x \oplus_p y) \oplus (x \oplus_p z) \} \\ &\approx ((M \oplus_{\frac{2}{1+2n}} P) \oplus_{\frac{1+2n}{4n}} Q) \oplus (N \oplus_{\frac{1}{2n}} (P \oplus_{\frac{1}{2}} Q)) \\ &\quad \{ \text{by } x \oplus_p (y \oplus_q z) \approx (x \oplus_{\frac{p}{p+q-pq}} y) \oplus_{p+q-pq} z \}\end{aligned}$$

Follows

game $\sim \lambda_{n, \text{score}} \rightarrow$

$$\begin{aligned} &((\text{game } 1 \ 0 \oplus_{\frac{2}{1+2n}} \text{game } n+1 \ \text{score}+1) \oplus_{\frac{1+2n}{4n}} \text{game } n+1 \ \text{score}) \oplus \\ &(\text{score} \oplus_{\frac{1}{2n}} (\text{game } n+1 \ \text{score}+1 \oplus_{\frac{1}{2}} \text{game } n+1 \ \text{score})) \end{aligned}$$

and thus simpleGame \sim game.

Conclusions and Future Works

Conclusions

- We have proposed a notion of bisimulation that **generalizes most of the existing ones**.
- Such a notion of bisimulation is built over a formal notion of observation **parametric over monads and operations**. This abstract treatment is of methodological importance for the theory behind operational equivalences of programs.
- We proved a **full Abstraction** theorem and developed useful **up-to techniques**.

Future Works

- Quite a lot! But two main directions:
- Get rid of the inductive (dcpo) structure behind the notion of observation, thus relying only on **finality** of $CT(\mathcal{V})$.
- To do so, we need a better categorical formulation of the above theory.
- The other direction would like to get rid of the monadic and categorical structure, thus relying only on equational specifications.
- Here the problem is to come up with a good extension of a finitary equational theory \approx to infinitary terms.

Thank you very much for the attention!