

# Game Semantics Approach to Higher-Order Complexity

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# Introduction

- Computability and complexity are defined for **first-order functions** (i.e.  $\Sigma^* \rightarrow \Sigma^*$ ) in many different ways
- Same for **second-order functions**, e.g.  $(\Sigma^* \rightarrow \Sigma^*) \rightarrow \Sigma^*$  (to a lesser extent)
- For **third-order functions** and above?
  - a few incomplete attempts to define complexity
  - not even a unique notion of computability

# Motivations

- First-order is sufficient to define computability/complexity for countable sets (e.g. integers, finite graphs, matrices, etc.)
- Second-order is required for computations over some uncountable sets (e.g. real numbers)
- Higher orders are required for some "larger spaces", especially for complexity
- Higher-order functions appear naturally in functional programming languages

# First-order complexity

Several computational models, equivalent for complexity:

## Machine models:

Complexity = a bound on **running time** given  
a **bound** on the **input size**

## Function algebras:

Cobham 1965 : **bounded recursion on notation**

## Others

Logic-based (linear logic), program  
interpretations, etc.

# Second-order complexity

## Definition (Mehlhorn (1976))

$FPTIME_2 = [FPTIME, \text{Application}, \text{Composition}, \text{Extension}, \mathcal{R}]$

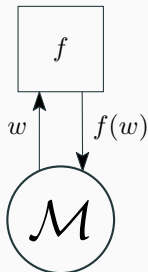
$$\mathcal{R}(x_0, F, B, x) \cdot \begin{cases} x_0 & \text{if } x = 0 \\ t & \text{if } |t| \leq B(x) \\ B(x) & \text{otherwise.} \end{cases}$$

where  $t = F(x, \mathcal{R}(x_0, F, B, \lfloor \frac{x}{2} \rfloor))$ .

## Theorem (Kapron & Cook 1996)

$FPTIME_2$  is the class of functions computed by an *oracle Turing machine* in second-order polynomial time.

# Oracle Turing machine



## Definition

$F : (\Sigma^* \rightarrow \Sigma^*) \rightarrow \Sigma^*$  is computed by an **oracle Turing machine**  $\mathcal{M}$  if for any oracle  $f : \Sigma^* \rightarrow \Sigma^*$ ,  $\mathcal{M}^f$  computes  $F(f)$ .

# Second order complexity

## Definition (Time complexity)

The **complexity** of a machine is an upper **bound** on its **computation time** w.r.t the **size** of its input.

- ✓ size of a finite word
- ? size of an order 1 function

# Second order complexity

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## Definition (Size of a function)

The **size** of  $f : \Sigma^* \rightarrow \Sigma^*$  is  $|f| : \mathbb{N} \rightarrow \mathbb{N}$ :

$$|f|(n) = \max_{|x| \leq n} |f(x)|.$$



# Second order polynomial time

## Definition (Second order polynomials)

$$P := c \mid X \mid Y\langle P \rangle \mid P + P \mid P \times P$$

## Example

$$P(X, Y) = (Y\langle X \times Y\langle X + 1 \rangle \rangle)^2$$

## Definition ( $\text{FPTIME}_2$ )

A second order function is **computable in polynomial time** if it is computed by an oracle Turing machine whose running time is bounded by a second order polynomial.

# Some higher order models

- Kleene schemata
- Kleene associates
- Berry-Curien sequential algorithms
- ...
- PCF (Scott, Plotkin)  
 $\lambda$ -calculus over  $\mathbb{N}$  + fixpoint combinator.  
✗ No simple underlying complexity notion.
- BFF (Cook, Urquhart)  
 $\lambda$ -calculus +  $\text{FPTIME}$  +  $\mathcal{R}$  ( $2^{\text{nd}}$ -order bounded recursion)  
✗ Defines only one complexity class (no  $\text{EXPTIME}$ , etc.)  
✗ Misses some intuitively feasible functionals.

## Example (Irwin, Kapron, Royer)

$$f_x(y) = 1 \iff y = 2^x$$

$$\Phi, \Psi : ((\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N}) \times \mathbb{N} \rightarrow \mathbb{N}$$

$$\Phi(F, x) = \begin{cases} 0 & \text{if } F(f_x) = F(\lambda y.0) \\ 1 & \text{otherwise.} \end{cases}$$

$$\Phi \in \text{BFF}_3$$

$$\Psi(F, x) = \begin{cases} 0 & \text{if } F(f_x) = F(\lambda y.0) \\ 2^x & \text{otherwise.} \end{cases}$$

$\Psi \notin \text{BFF}_3$ , but  $\Psi$  is "as feasible as"  $\Phi$ .

# The size issue

**Main issue:** No notion of size for functions of order 2 and above

In particular, for second-order, the modulus of continuity should be taken into account

**Solution:**

- A model where the **interaction** between machine and input is a **dialogue**.
- Size  $\simeq$  "length" of the dialogue.

# Computation = dialogue

O: What is  $f(x)$ ?

P: What is  $x$ ?

O:  $x$  equals 4.

P:  $f(x)$  equals 2.

**Figure 1:** Dialogue between a Turing machine (P) computing  $f$  and its opponent (O) computing  $x$ .

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...

P: What is  $f(x)$ ?

O: What is  $x$ ?

P:  $x$  equals 2.

O:  $f(x)$  equals 9.

P:  $F(f)$  equals 16.

**Figure 1:** Dialogue between an OTM (P) computing  $F$  and its opponent (O) computing  $f$ .

# Computation = dialogue

O: What is  $\Phi(F)$ ?

Second order dialogue ( $F(f_1)$ )

⋮

Second order dialogue ( $F(f_k)$ )

P:  $\Phi(F)$  equals 11.

**Figure 1:** Dialogue between an order 3 machine (P) computing  $\Phi$  and its opponent (O) computing  $F$ .

**Origin:** provide a fully abstract semantics for PCF

**Solution:** (Hyland & Ong, Nickau, Abramsky):

- functions  $\leftrightarrow$  strategies
- function application  $\leftrightarrow$  confrontation of strategies



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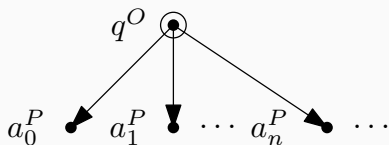
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Not made with effectivity/complexity in mind, although Nickau mentioned it.

An arena is a set of (player and opponent) moves (questions or answers) as well as a subset of initial questions and an enabling relation.

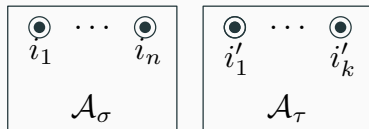
The answers enabled by an initial question are called final answers.

# Arenas for finite types



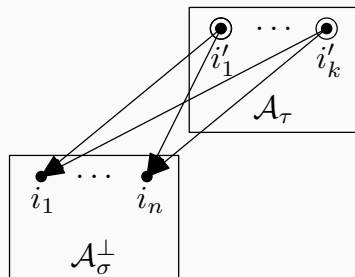
**Figure 2:** Arena for the base type  $\mathbb{N}$

# Arenas for finite types



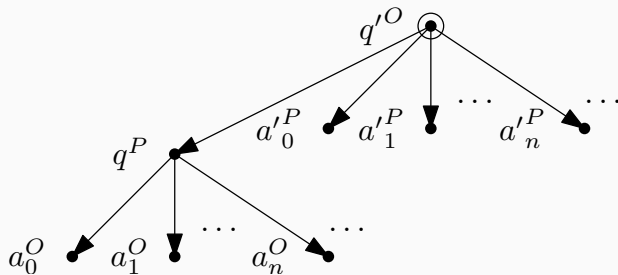
**Figure 2:** Arena  $\mathcal{A}_{\sigma \times \tau}$  built from  $\mathcal{A}_\tau$  and  $\mathcal{A}_\sigma$

# Arenas for finite types



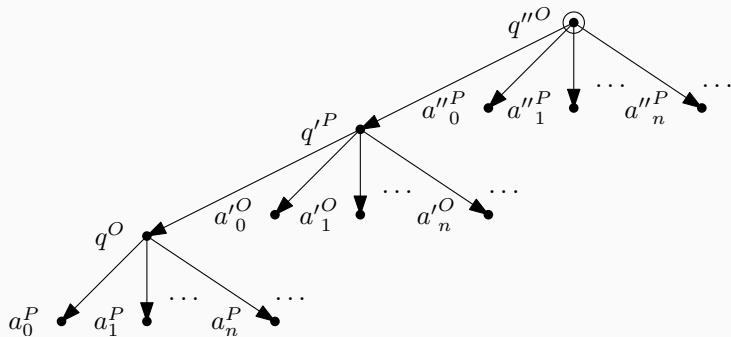
**Figure 2:** Arena  $\mathcal{A}_{\sigma \rightarrow \tau}$  built from  $\mathcal{A}_{\tau}$  and  $\mathcal{A}_{\sigma}$

# Arenas for finite types



**Figure 2:** Arena for type  $\mathbb{N} \rightarrow \mathbb{N}$

# Arenas for finite types



**Figure 2:** Arena for type  $(\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N}$

# Plays & Rules

## Definition (Play)

A **play** is a list of **named moves**, i.e.  $m[\alpha]$  ( $m \in \mathcal{A}, \alpha \in \mathbb{N}$ ).

A play  $p$  is said to be:

- **justified**: if every non initial move is justified by a previous move in  $p$  ;
- **well-opened**: if there is only one initial move, at the beginning of  $p$  ;
- **alternating**: if two consecutive moves belong to different protagonists ;
- **strictly scoped**: if answering a question prevents further moves to be justified by this question ;
- **strictly nested**: if question/answer pairs form a valid bracketing.



# Innocent Strategies

## Definition (Strategy)

A **strategy** is a partial function from plays to moves.

## Definition (Innocent strategy)

A strategy is **innocent** if its output only depends on its current **view** of the play.

# Confrontation

If  $\tau = \tau_1 \times \dots \times \tau_n \rightarrow \mathbb{N}$  and  $s, s_1, \dots, s_n$  are strategies on the arenas  $\mathcal{A}_\tau, \mathcal{A}_{\tau_1}, \dots, \mathcal{A}_{\tau_n}$ , then the **confrontation** of  $s$  against  $s_1, \dots, s_n$  is defined this way:

- the play  $p$  starts with the initial question of  $\mathcal{A}_\tau$
- the confrontation stops when  $s$  plays a final answer
- the play is successively extended this way:
  - if  $s$  is defined on  $p$ , then  $p$  is extended with  $s(p)$
  - if  $s(p)$  is not a final answer, it belongs to one of the  $\mathcal{A}_i$  and  $p$  contains a play  $p_i$  in  $\mathcal{A}_i$
  - the play is extended with  $s_i(p_i)$  (+renaming)

The final play  $H(s, s_1, \dots, s_n)$  is the **history of the confrontation**, and this defines a partial function  $s[\ ]$  from argument strategies to final answers.

Given a finite type  $\tau$ , the corresponding game is defined by **innocent strategies** playing **justified, alternating, well-opened, strictly-nested, ...** plays in the arena  $\mathcal{A}_\tau$ .

## Definition

Such a strategy  $s$  **represents**  $F : \tau_1 \times \cdots \times \tau_n \rightarrow \mathbb{N}$  if whenever  $s_1, \dots, s_n$  represent  $f_1 : \tau_1, \dots, f_n : \tau_n$ , then  $s[s_1, \dots, s_n]$  represents  $F(f_1, \dots, f_n)$

Our presentation of game semantics allows to define an explicit encoding of moves and names: for every game on a finite type  $\tau$ ,

- an answer of the form  $a_n$  (i.e. representing  $n \in \mathbb{N}$ ) can be encoded by a binary word of size  $\mathcal{O}(\log_2(n))$  ;
- the questions can be encoded by words of bounded size ;
- names are integers  $\rightarrow$  usual binary encoding ;
- this encoding can be extended to plays ;
- a strategy  $s$  can be represented by a partial function  $\bar{s}$  of type  $\Sigma^* \rightarrow \Sigma^*$

# Computability and complexity

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## Theorem

*Every computable function has a polynomial strategy.*

## Proof.

$s$  can gain time by asking many useless questions. □

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# Size of a strategy

## Definition (Size of a play)

= size of its binary encoding.

## Definition (Size of a strategy)

The **size**  $S_s$  of a strategy  $s$  in the game of type  $\tau = \tau_1 \times \dots \times \tau_n \rightarrow \mathbb{N}$  is a bound on the size of the play  $H$  produced by the confrontation of  $s$  versus **argument strategies**:

$$S_s(b_1, \dots, b_n) = \sup\{|H(s, s_1, \dots, s_n)| : \forall i, S_{s_i} \preceq_{\tau_i} b_i\}$$

Additionally, for all  $F, B : \tau$ ,  $F \preceq_{\tau} B$  if:

$$(\forall i, S_{s_i} \preceq_{\tau_i} b_i) \implies F(S_{s_1}, \dots, S_{s_n}) \leq B(b_1, \dots, b_n)$$

# Examples

## Example

- $k \in \mathbb{N}$  has a strategy of size about  $\log_2(k)$   
(plays are of the form:  $q, a_k[0]$ )
- $g : \mathbb{N} \rightarrow \mathbb{N}$  has a strategy of size about  
 $|g|(n) = \max_{|x| \leq n} |g(x)|$   
(plays are of the form:  $q, q'[0], a'_x[1], a_{g(x)}[0]$ )
- $F : (\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N}$  has a strategy whose size depends on  
its values and on its modulus of continuity.

## Definition (Game machine)

OTM which **simulates a strategy**:

- initial state  $\leftrightarrow$  initial question
- oracle call  $\leftrightarrow$  (encoded) player move
- oracle answer  $\leftrightarrow$  (encoded) opponent move
- final state + tape's content  $\leftrightarrow$  final answer

## Proposition

*s is simulated by a game machine  $\iff$  s is computable.*

# Complexity

We can define the **complexity of a strategy**, and in particular:

size  $\preceq$  complexity

size  $\simeq$  smallest relativized complexity

## Definition

$f \in \text{PCF}$  is **computable in time  $T$**  if there is a game machine simulating an innocent strategy for  $f$  in time  $T$ .

## Remark

*If  $s$  represents a PCF function  $f : \tau$ , then the size and complexity functions for  $s$  have type  $\tau$ .*

# Higher order polynomials

## Definition (Higher type polynomials)

HTP = simply-typed  $\lambda$ -calculus, with  $+$  and  $\times$ .

## Remark

- *Order 1 HTP = usual polynomials.*
- *Order 2 HTP = second order polynomials.*

# Higher order polynomial time complexity

## Definition (POLY)

$f \in \text{PCF}$  is **polynomial time computable** ( $f \in \text{POLY}$ ), if it has a strategy computed by a (higher order) polynomial time machine.

# Results

## Proposition

*For every finite type  $\tau$ , the complexity of the **identity** function of type  $\tau \rightarrow \tau$  is about  $\lambda b.2 \cdot b$ .*

Similarly, **composition**, **projections** and **expansion** also have polynomial time complexity.

## Remark

*If  $b : \sigma$  and  $B : \sigma \rightarrow \tau$  bound the complexity (resp. size) of  $f : \sigma$  and  $F : \sigma \rightarrow \tau$ , then  $B(b)$  bounds the complexity (resp. size) of  $F(f)$ .*

## Proposition

*Bounded recursion on notation is polynomial-time computable.*

## Proof.

It can be computed by  $|x|$  iteration of  $F$  applied to  $x$  an input bounded by the size of  $B$  on  $x$ . Its complexity is bounded by:

$$\lambda n_0 \lambda G \lambda H \lambda n. \quad n \cdot G(H(n, B(n) + n_0)) + n_0. \quad \square$$



## Theorem

- $FPTIME = BFF_1 = POLY_1$
- $FPTIME_2 = BFF_2 = POLY_2$
- $BFF \subseteq POLY$
- $BFF_3 \subsetneq POLY_3$  (cf. example  $\Psi$ )
- $POLY$  is stable by composition

$\implies$  this complexity class is a good candidate for a generalization of  $FPTIME$  at all finite types.

# Summary

We have defined:

- a **notion of size** for "PCF strategies" ;
- a **machine model** adapted to games ;
- a **notion of complexity** for PCF functions ;
- a **polynomial time computable** class for PCF.

This class verifies all the expected properties.

The notion of complexity is generic enough to define other classes like:

- exponential time
- sub-linear time (with smaller names?)
- space/non-deterministic complexity
- query/communication/... complexity

# Extension to more games

These notions extend to other kind of games as soon as:

- names, moves and plays have a binary encoding  
( $\implies$  countable arena)
- the confrontation can be defined:
  - finite-depth acyclic arena
  - well-opened, alternating, justified plays

In particular, strictly-nested plays or innocent strategies are not required to define size and complexity.

## Further work

- Further justify the relevance of POLY (e.g. provide characterizations)
- Study other (deterministic time) complexity classes
- Do higher-order classes help shed light on first-order classes?
- New complexity notions exclusive to higher-order
- Are there other meaningful "sequential games" than those for PCF?
- Generalize to other games, e.g. :
  - arenas with cycles  $\implies$  inductive/co-inductive types
  - no alternating rule  $\implies$  parallelism